

Aeronautical Engineering Final projects

- **SET-434.** Design of a low cost helmet mounted dead reckoning navigation system.
- **SET-466.** Autonomous Mobile Platform II with artificial intelligence using digital compass and GPS
- **SET-419.** Solar Tracker Robot using Microcontroller. **(2011)**
- SET-631. The Monitoring System design Of Harmful Gas inside Special Vehicle (2012)
- **SET-632**. Wireless Black Box Using MEMS Accelerometer and GPS Tracking for Accidental Monitoring of Vehicles **(2012)**
- SET-638. HAWK: An unmanned mini helicopter-based aerial wireless kit for localization (2012)
- **SET-627**. Field Variables Monitoring in real time (GPS, soil moisture, temperature) with Precision Farming Applications (2012)
- **SET-630**. Issues and Challenges of Wireless Sensor Networks Localization in Emerging Applications **(2012)**
- **SET-590**. An Accelerometer-Based Digital Pen with a Trajectory Recognition Algorithm for Handwritten Digit and Gesture Recognition (2012).
- SET-637. Design of Vehicle positioning System Based on ARM (2011)
- **SET-582.** Implementation of Tire Pressure Monitoring System with Wireless Communication. (IEEE-2011)
- **SET-497**. Material handling robot controlling through wireless Zigbee using MATLAB.
- **SET-529**. Construction of flying quad rotor with video surveillance system
- SET-531. Intelligently navigable Robotic vehicle for Industries using compass and RFID
- **SET-539.**RFID based instantaneous vehicle registration details extraction system
- **SET-541**.Intruder Tracking Using Wireless Sensor Networks
- **SET-547**. Ultrasonic Target Estimation Using Sonar Technology
- SET-548.Ultrasonic Target Range Estimation and Obstacle detection Robot
- **SET-553**.Implementation of Cryptography on PC using Zigbee
- **SET-572**.Object distance tracking system
- **SET-260**. Radar Velocity-measuring System Design and high speed alert intimation through SMS
- SET-258. Obstacle Avoidance and Manhole detection Electronic travel aid Robot for blind

www.mycollegeproject.com Ph: +91 9490219339, 040-23731030 Ameerpet: A-8, 2nd floor, Eureka court, beside Image hospital, Ameerpet, HYDERABAD – 73.

Dilsukhnagar: 203, Sreemaan Rama Towers, Opp: Kalanikethan, Chaitanyapuri, Dilsukhnagar, Hyderabad-62.

Santoshnagar: Opp: Big Bazaar, Santoshnagar X-Roads, HYDERABAD – 59.



- **SET-478.** Automatic brake comfort using ultrasonic sensor
- **SET-482.** Evidence collection from car block boxes using
- **SET-371.** PC controlled flying machine for weather monitoring system
- **SET-413.** GPS based Geo weather data logging in 2GB Memory card
- **SET-472**. MEMS Accelerometer controlled tilt sensing for Avionics applications
- **SET-454.** Servo Motor Control using mobile phone.
- **SET-223**. Missile detection and auto destroy system
- **SET-10.** Zigbee based wireless Voice to Text translator in Airlines/Hospital assistant system for blind/Illiterates.
- **SET-11.** Wireless GPS travel location data logger using Bluetooth/Zigbee.
- **SET-467.** Touch Screen based communication assistant in Airlines using high speed CAN communication
- SET-468. Solar-Assisted wireless communication assistant for Dumb/Illiterates in Airlines
- **SET-09.** Touch screen and Zigbee based wireless communication assistant for Dumb and illiterates in Airlines
- **SET-199.** Location aware mobile phone signal strength logger into 2GB memory card (MMC/SD/Micro SD)
- **SET-13.** Smart Card and GPS based automatic bus ticketing system for traveled distance.
- **SET-117.** Wireless vibration monitoring system of industrial equipments (Also useful for bridges monitoring).
- **SET-152.** Micro Electro Mechanical Sensor (MEMS) Accelerometer based self-balancing robot.
- **SET-200.** MEMS Accelerometer based digital photo frame with automatic position/view adjustment system (similar to digital cameras)
- **SET-501**. Flight parameters based on CAN protocol.
- **SET-502**. Real time implementation of CAN protocol in automobiles.
- **SET-511**. Vehicle dash board using CAN communication
- SET-583. CAN Based Distributed Control System For Autonomous All-Terrain Vehicle(ATV).
- **SET-584**. Industrial Automation Using CAN Protocol
- **SET-585.** Multivariable Parameter Interfacing With CAN Bus
- **SET-195.** CAN protocol enable multi-region monitoring and control system.