

Hall Effect Sensor based non-contact tachometer for electrical motors speed measurement

The purpose of this project is to design and construct a non-contact type of

Tachometer. A tachometer (also called a revolution-counter, rev-counter, or RPM gauge)

is an instrument that measures the rotation speed of a shaft or disk, as in a motor or other

machine. Hall Effect sensors typically use a rotating target attached to a wheel, gearbox

or motor. This target may contain magnets, or it may be a toothed wheel. The teeth on the

wheel vary the flux density of a magnet inside the sensor head.

This project consists of a Hall effect sensor connected to a microcontroller unit.

The sensor signals from Hall effect sensor are sent to microcontroller for rpm

measurement. These measured final values are displayed on a LCD display connected to

microcontroller.

A Hall effect sensor is a transducer that varies its output voltage in response to

changes in magnetic field. Hall sensors are used for proximity switching, positioning,

speed detection, and current sensing applications.

In its simplest form, the sensor operates as an analogue transducer, directly

returning a voltage. With a known magnetic field, its distance from the Hall plate can be

determined. Using groups of sensors, the relative position of the magnet can be deduced.

Electricity carried through a conductor will produce a magnetic field that varies

with current, and a Hall sensor can be used to measure the current without interrupting

the circuit. Typically, the sensor is integrated with a wound core or permanent magnet

that surrounds the conductor to be measured.

The project provides us exposure on the following:



- 1. Characteristics of Hall effect sensors.
- 2. LCD interfacing with micro controller
- 3. DC motor and Driver interfacings.
- 4. Embedded C programming.
- 5. PCB design.

The major building blocks of this project are:

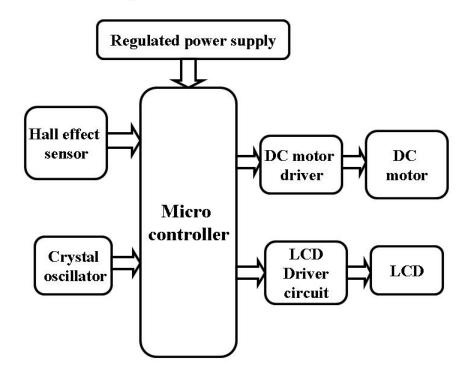
- 1. Regulated power supply.
- 2. Microcontroller.
- 3. Hall Effect Sensor.
- 4. LED indicators.
- 5. LCD interfacing.





Block diagram:

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